# MATHS LEARNING JOURNEY 

## USING ANGLE FACTS, SETS \& VENN DIAGRAMS

CALCULTING WITH FRACTIONS \& MIXED NUMBERS, CONSTRUCTING

FRACTIONS \& PERCENTAGES OF AMOUNTS,
DIRECTED NUMBER

## YEAR 7 MATHS LEARNING JOURNEY

| SETS AND VENN | PROBABILTY AND |
| :---: | :--- |
| DIAGRAMS | SAMPLE SPACES |$\quad$| IDENTIFY DIFFERENT |
| :--- |
| TYPES OF NUMBERS |

## YEAR 8 MATHS LEARNING JOURNEY

RATIO
MULTIPLICATIVE RELATIONSHIPS

## DIRECT PROPORTION

FORM AND SOLVE EQUATIONS

PROBABILTY PERCENTAGES

## YEAR 9 MATHS LEARNING JOURNEY

Y9

ONE AND TWO STEP INEQUALITIES

NETS, PLANS AND
ELEVATIONS

CALCULATING WITH FRACTIONS

PROBLEM SOLVING: INTEGERS AND DECIMALS

## YEAR 10 MATHS LEARNING JOURNEY

Y10
NON CALCULATOR METHODS

| CALCULATING |
| :---: |
| AVERAGES |$>$| EXPANDING |
| :--- |
| EXPRESSIONS |$>$| FACTORISING |
| :--- |
| EXPRESSIONS |

CHANGING THE SUBJECT

## TRIGONOMETRY

DIRECT PROPORTION

## YEAR 11 MATHS LEARNING JOURNEY



## A LEVEL MATHS LEARNING JOURNEY



Statistical distributions Differentiation
CLICK TO ADD SUB TOPIC INFO

Integration Forces \& Newton's Lows
CLICK TO ADD SUB TOPIC INFO

Exponentials \& Logarithms Kinematics: variable acceleration
CLICK TO ADD SUB TOPIC INFO


## YEAR 12 MATHS LEARNING JOURNEY

## Basic Algebra

## Surds \& Indices

Rules for indices. Simplifying with surds. Rationalising. Polynomials \& Graphs

Algebraic division. Factor theorem. Graphs of polynomials and transformations.

Kinematics: constant acceleration

Travel graphs, constant acceleration formulae and vertical motion under gravity.

Data processing \& interpretation
Statistical diagrams. Averages and measures of spread.
Comparisons of data. Large data set.

Coordinate Geometry
Distances, midpoints, gradients, lines and circles.

## Binomial Expansion

Expansion of $(a+b)^{n}$ where $n$ is
a positive integer.

Common graphs. Equations. Sine and cosine rules. Identities and proof.

## Probability

Tree diagrams, Venn diagrams. Independent events. Mutually exclusive events.


Forces \& Newton's Laws
Force diagrams. Resultant forces. Newton's laws of motion.
Connected particles including lifts, pulleys and towing.

Exponentials \& Logarithms
Definitions. Graphs of the form $y=a^{x}$. Logarithmic and exponential equations. Reduction to a linear form.

## Sampling \& Hypothesis Testing

Sampling techniques and their strengths and weaknesses. Hypothesis testing with the binomial distribution.

## Kinematics: variable

 accelerationUse of differentiation and integration in displacement/ velocity/acceleration problems.

More Trigonometry
Radians. Sectors and arcs. Small angle approximations. Sec, cosec and cot functions. Addition and double angle formulae. Related problems.

## Functions

Domain, range, composite and inverse functions. Modulus functions. Combined transformations.

Proof
Conjecture and counter-examples. Proof by deduction, exhaustion or contradiction.

Algebraic \& partial
fractions
Proper and improper fractions.
Separating into partial fractions.

## YEAR 13 MATHS LEARNING JOURNEY

Regression, Correlation $>$ Forces \& friction \& Hypothesis Testing
Linear and non-linear regression. Measuring correlation. Hypothesis testing for zero correlation.

Resolving forces. Forces on inclined planes. Friction. Applications.

## Sequences \& series

Arithmetic and geometric series. Infinite series. Recurrence relations. Periodic sequences.
Definitions. Cartesian and
parametric forms. Geometrical
problems. Differentiation.

Set notation. Conditional probability. Use of standard formulae and/or Venn diagrams and two-way tables.

## More differentiation

Chain Rule, product and quotient rules. Trigonometric, exponential and log differentiation. Implicit functions. Inflection. Related rates of change.

## More integration

Standard functions including trig, exponential and log integrals. Substitution, parts, inspection, partial fractions, parametric
integration and the trapezium rule.

## Vectors in 3D

Extension of Yr 12 work on 2D vectors. Geometrical problems.

## Revision

Full focus on revision and past exam papers in preparation for

A-level exams.

# A LEVEL MATHS WITH FURTHER MATHS LEARNING JOURNEY 

Basic Algebra
Binomial Expansion Coordinate Geometry


Proof by Induction
Critical Path Analysis

Exponentials \& Logarithms Matrices
Integration Forces \& Newton's Laws Further Algebra \& Functions Kinematics 2

Work, Energy \& Power Algorithms on Graphs

Momentum \& Impulse (1D)
Algorithms \& Graph Theory

Polar Coordinates Binomial Expansion

| Hyperbolic Functions | Kinematics in 2D | Numerical Methods |
| :---: | :---: | :---: |
| Momentum \& Impulse (2D) | Differential Equations | Moments |

Further Calculus Forces and Friction

## YEAR 12 MATHS WITH FURTHER MATHS LEARNING JOURNEY

Basic Algebra
Quadratic and
simultaneous equations. Inequalities.

Surds \& Indices
Rules for indices.
Simplifying with surds. Rationalising.

Binomial Expansion
Expansion of $(a+b)^{n}$ where n is a positive integer.

Coordinate<br>Geometry

Distances, midpoints, gradients, lines and circles.

Polynomials \& Graphs

Algebraic division. Factor theorem.
Graphs of polynomials and transformations.

## Statistical distributions

Common graphs. Equations. Sine and cosine rules.
Identities and proof. Links to mechanics.

Definitions. Direction and magnitude.
Geometrical problems
Links to mechanics.

Discrete distributions 8 probabilities. The binomial distribution and conditions for its use.

Probability
Data processing \& interpretation

Tree diagrams, Venn diagrams. Mutually exclusive and independent events.

Statistical diagrams. Averages and measures of spread. Comparisons of data. Large data set

## Differentiation $>$ Kinematics 1

Basic definitions. $1^{\text {st }}$ principles. Gradients on curves. Tangents, normals and stationary points.

Travel graphs, constant acceleration and vertical motion under gravity.
$\begin{gathered}\text { Sampling \& } \\ \text { Hypothesis Testing }\end{gathered}>$

Sampling techniques and their strengths and weaknesses. Hypothesis testing with the binomial distribution.

Further Algebra \& Functions

Sums and products of roots of polynomial equations.

Kinematics 2
Use of differentiation and integration in mechanics.

Introduction.
$2 \times 2$ and $3 \times 3$.
Transformations.
Sim eq'ns.

Momentum \& Impulse (1D)

Conservation of momentum for 2
spheres colliding directly.

Algorithms on Graphs

Kruskal's, Prim's and Dijkstra's algorithms. Chinese Postman.

Exponentials \& Logarithms Definitions. $y=a^{x}$ graph. Logarithmic and exponential equations.
Reduction to linear form.

Forces \& Newton's
Force diagrams. Resultant forces. Newton's laws of motion. Connected particles.

## Algorithms \& Graph Theory

Terminology. Sorting algorithms. Graph theory.


Kinetic and potential energy. Conservation of energy. Power, including inclined planes.

Further Calculus
Volumes of revolution.


Lines and planes. Scalar Graphs of inequalities. products. Intersections, Forming inequalities. angles and distances.

## Linear Programming Optimisation.

Complex Numbers

Definitions.
Conjugate pairs.
Argand diagrams. Analysis

Activity networks, critical paths. Gantt charts..

## Elastic Collisions (1D <br> Proof by Induction

Restitution. Successive direct impacts between spheres or a sphere and a surface.

Including sum of series, divisibility and powers of matrices.

## Functions

Domain, range, composite and inverse functions. Modulus functions.
Combined transformations.

## More Trigonometry

Radians. Sectors/arcs. Sec, cosec and cot. Addition and double angle formulae. Related problems.

Regression, Correlation \& Hypothesis Testing

Linear and non-linear regression. Measuring correlation. Hypothesis testing for zero correlation.

## Probability

Set notation. Conditional probability. Use of standard formulae and/or Venn diagrams and two-way tables.

Distribution
Definitions. Probabilities. Approximating binomial distributions. Hypothesis testing

## Proof Algebraic \&

 Partial FractionsConjecture and counterexamples. Proof by deduction, exhaustion or contradiction.

Proper and improper fractions. Separating into partial fractions.

## More

Differentitation
Chain Rule, product and quotient rules. Trigonometric, exponential and log differentiation. Implicit functions. Inflection. Related rates of change.

# YEAR 13 MATHS WITH FURTHER MATHS LEARNING JOURNEY 

## Y1 3

 More IntegrationStandard functions including trig, exp and log integrals. Substitution, parts, inspection, partial fractions, parametric integration and the trapezium rule.

## Parametric Equations

Definitions. Cartesian and parametric forms. Geometrical problems. Differentiation.

## Further Algebra

Method of differences. Maclaurin series

Sequences and Series
Arithmetic and geometric series. Infinite series. Recurrence relations. Periodic sequences.

## Vectors in 3-D

Extension of Yr 12 work on 2D vectors.
Geometrical problems

## More Complex Numbers

Exponential form. De Moivre's theorem. Applications to trigonometric. Roots of unity.

Polar Coordinates
Cartesian and polar conversion. Area enclosed by a polar curve.

Binomial Expansion
Expansion of $(a+b)^{n}$ where $n$ is rational or negative. Links with partial fractions.

## Further Calculus

Improper integrals. Mean value. Using partial fractions. Inverse trigonometric integration. More volume of revolution.


## Numerical Methods

Finding approximate answers to equations by numerical methods. Iteration. Newton-Raphson.

## Forces and Friction

Resolving forces. Forces on inclined planes. Friction. Applications.

## Differential Equations

Forming and solving $1^{\text {st }}$ order differential equations. Practical applications and modelling.

Hyperbolic Functions
Definitions. Graphs. Logarithmic form. Calculus with hyperbolics.

## Travelling Salesperson

Nearest neighbour algorithm. Upper and lower bounds.

Elasticity
Hooke's law and elastic potential energy. Work-energy principle and problem-solving in context.

## Graphs and Networks

Planarity algorithm. Route inspection with more than 4 odd nodes.

Momentum \& Impulse (2D)
Using vectors for momentum and impulse problems.

## Further Differential Equations

$1^{\text {st }}$ and $2^{\text {nd }}$ order differential equations. Applications to kinematics including harmonic motion. Coupled $1^{\text {st }}$ order simultaneous equations.

## Simplex Algorithm

Formulating. Simplex method. Integer solution problems. Twostage simplex method. Big-M.

## Revision

Full focus on revision and past exam papers in preparation for Critical Path Analysis

Resource histograms. Scheduling diagrams.

## Elastic Collisions (2D)

Oblique impacts between spheres or between spheres and surfaces. Use of scalar products.

